

## RCS Actuators

Versatile Automation Solutions
Electric Actuators
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## RCS Electric Actuators - Exceptional Automation Solutions

RCS actuators, a division of Dresser Utility Solutions, provides exceptional automation solutions for valve and equipment manufacturers and end users in the commercial, industrial, marine, and power applications.

Applicable to a myriad of automation solutions from simple on/off control to severe and critical modulating service, RCS actuators are suitable for use in a wide variety of challenging and hazardous environments. RCS actuators has specialized in offering engineered actuator solutions for unique and unusual applications for over 50 years and are proudly manufactured in America.

## Versatile and Reliable Electric Rotary Actuators

The RCS electric actuator rotary product line offers a broad selection of versatile actuator products. Targeted to quarter-turn and multi-turn valves and dampers, RCS actuators are also configurable for use in automating other types of flow control devices, and cover torque ranges from 25 lb . in. to $48,000 \mathrm{lb}$. in. with torque ranges from 120 lb . in. to $48,000 \mathrm{lb}$. in. with stroke speeds ranging from 0.5 seconds for 90 degree operation to 160 seconds for 90 degree operation, and for multi-turn versions, from 7.5 to 30 rpm .

## The Industry Leader in Spring-Return Actuators for Critical Isolation Service

RCS's SurePowr ${ }^{\otimes}$ spring-return electric actuators utilize heat treated alloy steel springs to assure a reliable mechanical solution for shutoff or isolation situations. This design provides a cost-effective, low maintenance, proven alternative to pneumatic, hydraulic, electro-hydraulic or battery fail-safe methods. The SurePowr series is capable of performance in elevated temperatures up to $400^{\circ} \mathrm{F}\left(250^{\circ} \mathrm{C}\right)$ for one hour without the need for external thermal insulation; up to four hours with external thermal insulation, and also for different durations at higher temperatures in compliance with NFPA 130 and NFPA 502; low temperature versions are also available.

## An Extensive Selection of Control Devices and Accessories

RCS offers an extensive selection of electrical and electronic accessories for its actuator selection, including the latest solutions to industry demands for analog and digital control protocols such as Modbus ${ }^{\circledR}$, Devicenet ${ }^{\oplus}$, and Profibus DP ${ }^{\oplus}$, in addition to relays, potentiometers, and other devices.

## Features \& Benefits

## Application Flexibility

RCS actuators from Dresser Utility Solutions provides a diverse range of torques, speeds and available voltages. Coupled with an extensive line of control and communication accessories, these actuators offer unique solutions to a host of automation requirements. Standard operation for MAR and DCR models is part turn, reversible with unidirectional and multi-turn options available.

## Electric Motors

All RCS electric actuators are powered by an extended duty, high-torque, reversible motor. These motors are suitable for both on/off and positioning applications. Each motor is Class " $B$ " insulated with an internal thermal overload protective device. This device protects the motor if a "stall" condition occurs, thus preventing the motor from overheating which could result in premature motor failure.

## Precision Gearing

All gears used in RCS actuators are manufactured from alloy steel. Each gear is precision machined and then heat-treated, giving the gears exceptional strength. Each gear assembly is designed to withstand the stall torque generated by the motor.

## Permanent Lubrication

All gear and spring assemblies are permanently lubricated with a high quality lubricant selected to meet a wide range of operational and environmental conditions. Periodic lubrication is not required.

## Versatile Installation

All RCS actuators can be installed and operated in any position. This allows flexibility for installation in confined locations or in retrofit applications.

## Manual Override

MAR/DCR 10, 50 and 90 models feature a engageable manual override. The actuator gearing is disengaged from the motor, thus the actuator cannot be operated electrically while in manual operation. MAR 100 through 4000 feature a manual override with an automatic electrical safety lockout switch. When the handwheel is engaged, the electrical switch isolates the motor from the supply voltage to prevent electrical operation.

## Environmental

With electrostatically applied powder coating, electroless nickel-plated output shafts, and stainless steel external fasteners, optional marine epoxy paint systems or electroless nickel plated enclosures are also available to meet most onshore or offshore conditions.

## Position Indication

Mechanical position indicators are standard on every model. An external indicator provides a visual reference for the actuator position.

## Simplified Wiring

All RCS actuators feature internal wiring connected to a clearly marked and easily accessible terminal strip to provide for convenient termination of field wiring.

## Part-Turn Electric | Multi-Turn Electric

Optional 7" Handwheel Available


| NEMA 7 Enclosure |  |
| :--- | :--- |
|  | Approvals |
| MAR Models Only |  |
| (Canadian Standards Association) |  |




Positioning


Multi-Turn

## Part-Turn Electric | Multi-Turn Electric

Outline Dimensions (Inches) - MAR \& DCR 10, 50, \& 90

| Weight |
| :--- |
| NEMA 4/4X Enclosure: $12 \mathrm{lbs} . / 5.4 \mathrm{~kg}$ |
| NEMA 7 Enclosure: $16 \mathrm{lbs} . / 7.3 \mathrm{~kg}$ |



## Mounting Geometry - Bottom View



## Notes

1. Direction of rotation is based on viewing actuator from top.
2. Drawing shows output shaft in a fully clockwise (closed) position.
3. Actuator shown with indicator in electrical mode.
4. A NEMA 4 control enclosure is shown. Dimensions given are accurate for NEMA 7.

## Part-Turn Electric | Multi-Turn Electric

115 \& 230 VAC, 1 Phase, $50 / 60 \mathrm{~Hz}$.

| Model | Output <br> Torque Inch Pounds (N.m) | Type | $\begin{gathered} \text { Speed of } \\ \text { Operation } \\ 60 \mathrm{~Hz} .(50 \mathrm{~Hz} .) \end{gathered}$ | Duty Cycle Rating 115 Vac, 1Ph., 50/60 Hz. | Duty Cycle Rating 230 Vac, 1Ph., 50/60 Hz . | Current Ratings 115 VAC |  | Current Ratings 230 VAC |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | NLA* | LRA* | NLA* | LRA* |
| MAR 10.5MT | 25 (3.01) | Multi-Turn | $\begin{gathered} 30 \text { RPM } \\ \text { N/A } \end{gathered}$ | $25 \%$ <br> (2) | $25 \%$ <br> (2) | 0.50 | 0.82 | 0.25 | 0.40 |
| MAR 10-2 | 120 (13.6) | Part Turn | $\begin{gathered} 2 \text { second } / 90^{\circ} \\ \left(2.5 \text { seconds } / 90^{\circ}\right) \end{gathered}$ | 50\% <br> (1) | 50\% <br> (1) | 0.40 | 0.60 | 0.30 | 0.40 |
| MAR 10-2MT | 120 (13.6) | Multi-Turn | $\begin{gathered} \text { 7.5 RPM } \\ \text { (6.2 RPM) } \end{gathered}$ | 50\% <br> (2) | 50\% <br> (2) | 0.40 | 0.60 | 0.20 | 0.25 |
| MAR 10-10 | 350 (39.5) | Part Turn | 10 seconds $/ 90^{\circ}$ <br> ( 12 seconds $/ 90^{\circ}$ ) | $50 \%$ <br> (1) | $50 \%$ <br> (1) | 0.40 | 0.60 | 0.20 | 0.25 |
| MAR 10-30 | 425 (48.0) | Part Turn | 30 seconds $/ 90^{\circ}$ <br> ( 35 seconds $/ 90^{\circ}$ ) | $50 \%$ <br> (2) | $50 \%$ <br> (2) | 0.30 | 0.50 | 0.20 | 0.25 |
| MAR 10-60 | 400 (45.2) | Part Turn | 60 seconds $/ 90^{\circ}$ <br> (70 seconds/90 $)$ | $50 \%$ <br> (2) | $50 \%$ <br> (2) | 0.35 | 0.55 | 0.20 | 0.25 |
| MAR 50.5MT | 200 (22.6) | Multi-Turn | $\begin{gathered} 30 \text { RPM } \\ \text { N/A } \end{gathered}$ | $25 \%$ <br> (2) | 25\% | 1.90 | 3.10 | - | - |
| MAR 50-2 | 600 (67.8) | Part Turn | 2 seconds/ $90^{\circ}$ <br> ( 2.5 seconds $/ 90^{\circ}$ ) | 40\% <br> (1) | 50\% <br> (1) | 1.60 | 2.20 | 0.50 | 0.95 |
| MAR 50-2MT | 600 (67.8) | Multi-Turn | $\begin{aligned} & \text { 7.5 RPM } \\ & \text { (6.2 RPM) } \end{aligned}$ | $40 \%$ <br> (2) | 50\% <br> (2) | 1.60 | 2.20 | 0.50 | 0.95 |
| MAR 50-10 | 600 (67.8) | Part Turn | $\begin{gathered} 10 \text { seconds } / 90^{\circ} \\ \left(12 \text { seconds } / 90^{\circ}\right. \text { ) } \end{gathered}$ | $50 \%$ <br> (1) | $50 \%$ <br> (1) | 0.50 | 0.80 | 0.30 | 0.50 |
| MAR 50-30 | 700 (79.1) | Part Turn | $\begin{gathered} 30 \text { seconds } / 90^{\circ} \\ \left(35 \text { seconds } / 90^{\circ}\right. \text { ) } \end{gathered}$ | $50 \%$ <br> (2) | $50 \%$ <br> (2) | 0.35 | 0.55 | 0.20 | 0.25 |
| MAR 50-60 | 600 (67.8) | Part Turn | $\begin{aligned} & 60 \text { seconds/ } 90^{\circ} \\ & \left(70 \text { seconds } / 90^{\circ}\right. \text { ) } \end{aligned}$ | $50 \%$ <br> (2) | $50 \%$ <br> (2) | 0.30 | . 50 | 0.20 | 0.25 |
| MAR 90-5 | 1,000 (113.0) | Part Turn | 5 seconds/ $90^{\circ}$ <br> ( 6 seconds/ $90^{\circ}$ ) | 50\% <br> (1) | 50\% <br> (1) | 0.55 | 1.55 | 0.25 | 0.85 |
| MAR 90-5MT | 1,000 (113.0) | Multi-Turn | $\begin{gathered} 3 \mathrm{RPM} \\ \text { (2.5 RPM) } \end{gathered}$ | 50\% <br> (2) | 50\% <br> (2) | 0.55 | 1.55 | 0.25 | 0.85 |
| MAR 90-15 | 1,000 (113.0) | Part Turn | 15 seconds $/ 90^{\circ}$ <br> (17.5 seconds/ $90^{\circ}$ ) | 75\% <br> (2) | 50\% <br> (2) | 0.50 | 0.60 | 0.20 | 0.35 |

* (N.L.A.) - No Load Ampere (L.R.A.) — Locked Rotor Ampere (1) - Open/Close Service (2) - Open/Close or Positioning Service


## Isolation Relays

To operate multiple actuators in parallel from a single signal requires isolating relays in the actuator or the field wiring.

## Duty Cycle

The percentage of time the electric motor is energized vs. the time it is at rest, in reversing duty, and with the actuator running at the rated maximum published torque.

## Standard Modulating Duty Rating

12 motor starts (corrections) per minute at the rated duty cycle for that model with the speed of operation a minimum of 15 seconds for $90^{\circ}$ or slower with positioning accuracy of (+/-) $1 \%$ of total span.

Note - Multi-turn models are available with the following number of turns:
$1.4,5,8,13,18,26$ or 50 . This must be specified when the order is placed.

## Part-Turn Electric | Multi-Turn Electric

12 \& 24 VDC

| Model | Output Torque Inch Pounds (N.m) | Type | No Load Speed of Operation | Duty Cycle Rating 12 VDC | Duty Cycle Rating 24 VDC | Current Ratings$12 \mathrm{VDC}$ |  | Current Ratings 24 VDC |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | NLA* | LRA* | NLA* | LRA* |
| DCR 10-2 | 250 (28.2) | Part Turn | . 6 seconds/ $/ 90^{\circ}$ | 50\% (1) | 50\% (1) | 1.00 | 12.3 | 0.75 | 6.80 |
| DCR 10-2MT | 250 (28.2) | Multi-Turn | 25 RPM | 50\% (2) | 50\% (2) | 1.00 | 12.3 | 0.75 | 6.80 |
| DCR 10-10 | 400 (45.2) | Part Turn | 6.4 seconds $/ 90^{\circ}$ | 50\% (1) | 50\% (1) | 0.19 | 3.90 | 0.08 | 2.10 |
| DCR 50-2 | 600 (67.8) | Part Turn | . 7 seconds/90 | 50\% (1) | 50\% (1) | 1.53 | 22.00 | 0.75 | 12.30 |
| DCR 50-2MT | 600 (67.8) | Multi-Turn | 21 RPM | 50\% (2) | 50\% (2) | 1.53 | 22.00 | 0.75 | 12.30 |
| DCR 50-10 | 600 (67.8) | Part Turn | 5.6 seconds $/ 90^{\circ}$ | 50\% (1) | 50\% (1) | 0.90 | 5.60 | 0.5 | 2.10 |
| DCR 50-30 | 700 (79.1) | Part Turn | 21 seconds/90 ${ }^{\circ}$ | 50\% (2) | 50\% (2) | 0.15 | 2.65 | 0.06 | 1.15 |
| DCR 90-5 | 900 (101.7) | Part Turn | 2.2 seconds $/ 90^{\circ}$ | 50\% (1) | 50\% (1) | 1.00 | 12.50 | 0.75 | 6.60 |
| DCR 90-5MT | 900 (101.7) | Multi-Turn | 7 RPM | 50\% (2) | 50\% (2) | 1.00 | 12.50 | 0.75 | 6.60 |
| DCR 90-15 | 900 (101.7) | Part Turn | 5.6 seconds $/ 90^{\circ}$ | 50\% (2) | 50\% (2) | 0.90 | 5.60 | 0.50 | 2.10 |

* (N.L.A.) - No Load Ampere (L.R.A.) - Locked Rotor Ampere (1) - Open/Close Service (2) - Open/Close or Positioning Service


## Limit Switches (MAR Models)

Standard: Two-single pole, double throw type (SPDT) with an option for 2 or 4 additional.
Ratings: UL and CSA listed.
$15 \mathrm{amp} \& 1 / 2$ H.P. at 125 or 250 VAC;
$1 / 2 \mathrm{amp}$ at 125 VDC ;
$1 / 4 \mathrm{amp}$ at $250 \mathrm{VDC} ; 5 \mathrm{amp}$ at 120 VAC
Optional: All double pole, double throw type (DPDT).
Ratings: UL and CSA listed.
10 amp at 125/250 VAC (form ZZ); 1/2 H.P. at 125 VDC; $3 / 4$ H.P. at 250 VAC

## Limit Switches (DCR Models)

Ratings: Ratings: UL and CSA listed. MIL-PRF-8805 Qualified Listing 25 amp at $277 \mathrm{VAC} ; 1$ H.P. at 125 VAC ; 2 H.P. at 250 VAC

## Isolation Relays

## To operate multiple actuators in parallel from a single signal requires isolating relays in the actuator or the

 field wiring.
## Duty Cycle

The percentage of time the electric motor is energized vs. the time it is at rest, in reversing duty, and with the actuator running at the rated maximum published torque.

## Standard Modulating Duty Rating

12 motor starts (corrections) per minute at the rated duty cycle for that model with the speed of operation a minimum of 15 seconds for $90^{\circ}$ or slower with positioning accuracy of (+/-) $1 \%$ of total span.

Note - Multi-turn models are available with the following number of turns:
$1.4,5,8,13,18,26$ or 50 . This must be specified when the order is placed.

## Part-Turn Electric | Multi-Turn Electric



## NEMA 4 Enclosure

Approvals
MAR Models Only (Canadian Standards Association)
CSA NRTL/C Type 4


CSA NRTL/C Approved to UL Standard No. 1203, Electrical Equipment for use in Explosion - proof And Dust - Ignition - proof Hazardous (Classified) Locations

## NEMA 4/4X/6/7 Enclosure

Approvals
MAR Models Only
(Canadian Standards Association)

| CSA NRTL/C | Type 4/4X and 6 |
| :--- | :--- |
| CSA NRTL/C | $\begin{array}{l}\text { Class I, Division 1, } \\ \text { Groups C \& D }\end{array}$ |

CSA NRTL/C $\begin{gathered}\text { Class II, Division 1, } \\ \text { Groups E, F \& G }\end{gathered}$ Groups E, F \& G
CSA NRTL/C Approved to UL Standard No. 429, Electrically Operated Valves
 Valves

| Models |  |
| :--- | :--- |
| A.C. Voltages | D.C. Voltages |
| MAR-100 | DCR-100 |
| MAR-120 | DCR-160 |
| MAR-160 | DCR-250 |
| MAR-250 | DCR-800 |
| MAR-800 |  |
| Typical Applications |  |

For open / Close or positioning control of:

- Part turn ball, butterfly, choke or plug valves
- Multi-turn valve types
- Ventilation dampers
- Select Multi-turn Valves

Temperature Range
Standard: $-40^{\circ} \mathrm{F}$ to $+150^{\circ} \mathrm{F}$ $-40^{\circ} \mathrm{C}$ to $+66^{\circ} \mathrm{C}$
Optional: $-60^{\circ} \mathrm{F}$ to $+120^{\circ} \mathrm{F}$
$-51^{\circ} \mathrm{C}$ to $+49^{\circ} \mathrm{C}$
(Note: With heater installed and energized)
Optional: Compliance to NFPA 130 and NFPA 502, capable of operation after exposure to ambient temperature of $482^{\circ} \mathrm{F}\left(250^{\circ} \mathrm{C}\right)$ for a minimum of 1 hour

| Voltage |
| :--- |
| $115 \mathrm{VAC}, 1$ Phase, $50 / 60 \mathrm{~Hz}$. |
| $230 \mathrm{VAC}, 1$ Phase, $50 / 60 \mathrm{~Hz}$. |
| $220 \mathrm{VAC}, 3$ Phase, 60 Hz. |
| $440 \mathrm{VAC}, 3$ Phase, 60 Hz. |
| 12 VDC |
| 24 VDC |
| Torque Range |
| 1,500 to 10,000 inch pounds |
| (169.5 to 1129.8 newton meters) |
| Speed Range |
| For 60 Hz. operation: |
| 1.25 to 60 seconds for $90^{\circ}$ revolution |
| 5 to 12 RPM for multi-turns |
| Standard Features |
| AC (Single and Three Phase ) Voltages |
| $4-$ SPDT Switches, PTC Heater |
| DC Voltages, $4-$ SPDT (High Current) |
| Switches, Handwheel manual override |
| with electrical isolation |



## Part-Turn Electric | Multi-Turn Electric

Outline Dimensions (Inches) - MAR \& DCR 100, 120, 160 \& 250



Mounting Geometry


## Notes

1. Drawing shows the actuator output shaft in a fully clockwise (closed) position.
2. Direction of actuator rotation is based on the top view from the handwheel.
3. A NEMA 4 control cover is shown.

Dimensions given are accurate for NEMA 4/6/7.
4. Actuator is shown with handwheel in electrical mode.

Height is $13.0^{\prime \prime}$ when manual override is used.

## Part-Turn Electric | Multi-Turn Electric

Outline Dimensions (Inches) - MAR \& DCR 800

| Weight |
| :--- |
| NEMA 4 Enclosure: $34 \mathrm{lbs} / 15.4 \mathrm{~kg}$ |
| NEMA $4 / 6 / 7$ Enclosure: $44 \mathrm{lbs} / 20 \mathrm{~kg}$ |




## Mounting Geometry



## Notes

1. Drawing shows the actuator output shaft in a fully clockwise (closed) position.
2. Direction of actuator rotation is based on the top view from the handwheel.
3. A NEMA 4 control cover is shown. Dimensions given are accurate for NEMA 4/6/7.
Actuator is shown with handwheel in electrical mode. Height is $13.3^{\prime \prime}$ when manual override is used.

## Part-Turn Electric



## NEMA 4/6/7 Enclosure

Approvals
A.C. Models
(Canadian Standards Association)

| NEMA 4/6/7 Enclosure |  |
| :--- | :--- |
|  | Approvals |
| A.C. Models |  |
| (Canadian Standards Association) |  |

CSA NRTL/C Class II, Division 1, Groups E, F \& G

CSA NRTL/C Approved to UL Standard No. 429, Electrically Operated Valves

CSA NRTL/C Approved to UL Standard No. 1203, Electrical Equipment for use in Explosion - proof And Dust - Ignition - proof Hazardous (Classified) Locations

| Models |
| :---: |
| MAR 1600, MAR 4000 |
| Typical Applications |
| For open / close or positioning control of: <br> - Part turn ball, butterfly or plug valves <br> - Rotary dampers |
| Temperature Range |
| Standard: $-40^{\circ} \mathrm{F}+150^{\circ} \mathrm{F}$ <br>  $-40^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}$ <br> Optional: $-60^{\circ} \mathrm{F}$ to $+150^{\circ} \mathrm{F}$ <br>  $-50^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}$ |
| Voltage |
| 115 VAC, 1 Phase, $50 / 60 \mathrm{~Hz}$. 230 VAC, 1 Phase, $50 / 60 \mathrm{~Hz}$. 220 VAC, 3 Phase, 60 Hz . 440 VAC, 3 Phase 60 Hz . |
| Torque Range |
| 21,000 to 48,000 inch pounds (2,373 to 5,424 newton meters) |
| Speed Range |
| 70 \& 160 seconds for $90^{\circ}$ revolution |
| Standard Features |
| AC (Single or Three Phase) Voltages <br> 4 - SPDT Switches, Thermostatically controlled PTC heater Handwheel manual override with electrical isolation |



## Part-Turn Electric

Outline Dimensions (Inches) - MAR 1600-65 and 4000-160

| Weight |
| :--- |
| NEMA 4/4X/6/7 Enclosure: $126 \mathrm{lbs} / 57.2 \mathrm{~kg}$ |

- 10.0 Clearance for cover removal



## Mounting Geometry



## Notes

1. Drawing shows the actuator output shaft in a fully clockwise (closed) position.
2. Direction of actuator rotation is based on the top view of the eternal gearbox.
3. Actuator is shown with handwheel in electrical mode.
Height is $2.4^{\prime \prime}$ when manual override is used.

## Part-Turn Electric | Multi-Turn Electric

115 \& 230 VAC, 1 Phase, 50/60 Hz.

| Model | Output <br> Torque Inch Pounds (N.m) | Type | $\begin{gathered} \text { Speed of } \\ \text { Operation } \\ 60 \mathrm{~Hz} .(50 \mathrm{~Hz} .) \end{gathered}$ | Duty Cycle Rating 115 Vac, 1Ph., $50 / 60 \mathrm{~Hz}$. | Duty Cycle Rating 230 Vac, 1Ph., $50 / 60 \mathrm{~Hz}$. | Current Ratings 115 VAC |  | Current Ratings 230 VAC |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | NLA* | LRA* | NLA* | LRA* |
| MAR 100-16 | 1,500 (169) | Part Turn | 16 seconds $/ 90^{\circ}$ $\left(19\right.$ seconds $\left./ 90^{\circ}\right)$ | $\begin{gathered} 100 \% \\ (2) \end{gathered}$ | $50 \%$ <br> (2) | 0.55 | 1.55 | 0.25 | 0.85 |
| MAR 100-30 | 1,800 (203) | Part Turn | 30 seconds $/ 90^{\circ}$ <br> ( 35 seconds $/ 90^{\circ}$ ) | 100\% <br> (2) | 50\% <br> (2) | 0.50 | 0.60 | 0.30 | 0.35 |
| MAR 100-60 | 2500 (282) | Part <br> Turn | 60 seconds $/ 90^{\circ}$ <br> (70 seconds/90 ${ }^{\circ}$ ) | $100 \%$ <br> (2) | 50\% <br> (2) | 0.35 | 0.55 | 0.20 | 0.35 |
| MAR 120-1.25 | 1,500 (169) | Part <br> Turn | 1.25 seconds $/ 90^{\circ}$ <br> (2 seconds/90 ${ }^{\circ}$ ) | $25 \%$ <br> (1) | $25 \%$ <br> (1) | 3.30 | 7.40 | 1.30 | 3.60 |
| $\begin{gathered} \text { MAR 120-1.25 } \\ \text { MT } \end{gathered}$ | 1,500 (169) | MultiTurn | 12 RPM (10 RPM) | $25 \%$ <br> (2) | $25 \%$ <br> (2) | 3.30 | 7.40 | 1.30 | 3.60 |
| MAR 160-8 | 1,920 (217) | Part <br> Turn | 8 seconds $/ 90^{\circ}$ <br> ( 9 seconds $/ 90^{\circ}$ ) | 50\% <br> (1) | 50\% <br> (1) | 0.75 | 1.65 | 0.70 | 1.05 |
| MAR 160-16 | 2,000 (226) | Part Turn | 16 seconds $/ 90^{\circ}$ <br> ( 19 seconds $/ 90^{\circ}$ ) | $75 \%$ <br> (2) | 50\% (2) | 0.60 | 1.60 | 0.35 | 0.90 |
| MAR 160-30 | 2,500 (282) | Part <br> Turn | 30 seconds $/ 90^{\circ}$ <br> ( 35 seconds $/ 90^{\circ}$ ) | $75 \%$ <br> (2) | 50\% <br> (2) | 0.65 | 0.70 | 0.45 | 0.50 |
| MAR 160-60 | 2,800 (316) | Part <br> Turn | 60 seconds $/ 90^{\circ}$ <br> (70 seconds/90 $)$ | $\begin{gathered} 100 \% \\ \text { (2) } \end{gathered}$ | $50 \%$ <br> (2) | 0.50 | 0.60 | 0.30 | 0.35 |
| MAR 250-3 | 3,500 (395) | Part <br> Turn | 3 seconds/90 <br> (4 seconds/90 ) | $25 \%$ <br> (1) | 50\% <br> (1) | 3.30 | 7.40 | 0.90 | 3.40 |
| MAR 250-3MT | 3,500 (395) | MultiTurn | 5 RPM (4 RPM) | $25 \%$ <br> (2) | 50\% <br> (2) | 3.30 | 7.40 | 0.90 | 3.40 |
| MAR 250-8 | 3,000 (339) | Part <br> Turn | 8 seconds $/ 90^{\circ}$ <br> ( 9 seconds $/ 90^{\circ}$ ) | 40\% <br> (1) | 50\% <br> (1) | 1.60 | 2.20 | 1.00 | 1.25 |
| MAR 250-16 | 4,000 (452) | Part <br> Turn | 16 seconds/90 ${ }^{\circ}$ <br> (19 seconds/90 ${ }^{\circ}$ ) | 50\% <br> (2) | 50\% <br> (2) | 1.10 | 1.80 | 0.70 | 1.05 |
| MAR 250-30 | 5,000 (565) | Part <br> Turn | 30 seconds $/ 90^{\circ}$ <br> ( 35 seconds $/ 90^{\circ}$ ) | 50\% <br> (2) | 50\% <br> (2) | 0.75 | 1.65 | 0.50 | 0.95 |
| MAR 250-60 | 5,000 (565) | Part <br> Turn | 60 seconds $/ 90^{\circ}$ (70 seconds/90 | $75 \%$ <br> (2) | 50\% <br> (2) | 0.65 | 0.70 | 0.30 | 0.35 |
| MAR 800-12 | 7,500 (847) | Part <br> Turn | 12 seconds $/ 90^{\circ}$ <br> ( 14 seconds $/ 90^{\circ}$ ) | 25\% <br> (1) | $25 \%$ <br> (1) | 3.30 | 7.40 | 0.90 | 3.40 |
| MAR8 00-30 | $\begin{aligned} & 10,000 \\ & (1,130) \end{aligned}$ | Part <br> Turn | 30 seconds $/ 90^{\circ}$ <br> ( 35 seconds $/ 90^{\circ}$ ) | $40 \%$ <br> (2) | 50\% <br> (2) | 1.60 | 2.20 | 1.00 | 1.20 |
| MAR 800-60 | $\begin{aligned} & 10,000 \\ & (1,130) \end{aligned}$ | Part <br> Turn | 60 seconds $/ 90^{\circ}$ <br> (70 seconds/90 ) | 75\% <br> (2) | 50\% <br> (2) | 0.55 | 1.55 | 0.50 | 0.95 |
| MAR 1600-70 | $\begin{aligned} & 21,000 \\ & (2,373) \end{aligned}$ | Part <br> Turn | 70 seconds $/ 90^{\circ}$ <br> ( 82 seconds $/ 90^{\circ}$ ) | $25 \%$ <br> (2) | 50\% <br> (2) | 3.30 | 7.40 | 0.90 | 3.40 |
| MAR 4000-160 | $\begin{aligned} & 48,000 \\ & (5,424) \end{aligned}$ | Part <br> Turn | $\begin{aligned} & 170 \text { seconds } / 90^{\circ} \\ & \left(200 \text { seconds } / 90^{\circ}\right. \text { ) } \end{aligned}$ | $25 \%$ <br> (2) | 50\% <br> (2) | 3.30 | 7.40 | 0.90 | 3.40 |
| L.A.) - No Load Ampere (L.R.A.) - Locked Rotor Ampere |  |  |  | (1) - Open/Close Service |  | (2) - Open/Close or Positioning Service |  |  |  |

## Duty Cycle

The percentage of time the electric motor is energized vs. the time it is at rest, in reversing duty, and with the actuator running at it's rated load maximum published torque.

## Standard Modulating Duty Rating

12 motor starts (corrections) per minute at the rated duty cycle for that model with the speed of operation a minimum of 15 seconds for $90^{\circ}$ or slower. With positioning accuracy of (+/-) $1 \%$ of total span

## Isolation Relays

To operate multiple actuators in parallel from a single signal requires isolating relays in the actuator or the field wiring.
Note - Multi-turn models are available with the following number of turns: $1.4,5,8,13,18,26$ or 50. Must be specified when the order is placed.

## Part-Turn Electric | Multi-Turn Electric

12 \& 24 VDC

| Model | Output Torque Inch Pounds (N.m) | Type | No Load Speed of Operation | Duty Cycle Rating 12 VDC | Duty Cycle Rating 24 VDC | Current Ratings 12 VDC |  | Current Ratings 24 VDC |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | NLA* | LRA* | NLA* | LRA* |
| DCR 100-30 | 2,000 (225) | Part Turn | 11.5 seconds/ $90^{\circ}$ | 50\% (2) | 50\% (2) | 0.90 | 5.80 | 0.50 | 2.10 |
| DCR 160-16 | 2,200 (248) | Part Turn | 5.5 seconds/ $90^{\circ}$ | 50\% (1) | 50\% (1) | 1.00 | 12.50 | 0.75 | 6.80 |
| DCR 160-60 | 3,600 (406) | Part Turn | 22 seconds/ $90^{\circ}$ | 50\% (2) | 50\% (2) | 0.90 | 5.80 | 0.50 | 2.10 |
| DCR 250-8 | 3,000 (339) | Part Turn | 3.2 seconds/90 ${ }^{\circ}$ | 50\% (1) | 50\% (1) | 1.53 | 22.00 | 0.75 | 12.00 |
| DCR 250-16 | 4,000 (452) | Part Turn | 5.7 seconds/ $90^{\circ}$ | 50\% (1) | 50\% (1) | 1.53 | 22.00 | 0.75 | 12.00 |
| DCR 250-30 | 5,000 (565) | Part Turn | 11.2 seconds/ $90^{\circ}$ | 50\% (2) | 50\% (2) | 1.00 | 12.50 | 0.75 | 6.60 |
| DCR 800-30 | 10,000 (1,130) | Part Turn | 13.3 seconds/ $90^{\circ}$ | 50\% (2) | 50\% (2) | 1.53 | 22.00 | 0.75 | 12.30 |
| DCR 800-60 | 10,000 (1,130) | Part Turn | 23 seconds/90 ${ }^{\circ}$ | 50\% (2) | 50\% (2) | 1.00 | 12.50 | 0.75 | 6.60 |

* (N.L.A.) - No Load Ampere (L.R.A.) - Locked Rotor Ampere (1) - Open/Close Service (2) - Open/Close or Positioning Service


## Limit Switches (MAR Models)

Standard: Four-single pole, double throw type (SPDT) with an option for 2 additional.
Ratings: UL and CSA listed.
$15 \mathrm{amp} \& 1 / 2$ H.P. at 125 or 250 VAC
$1 / 2$ amp at 125 VDC;
$1 / 4 \mathrm{amp}$ at 250 VDC
Lamp Load: 5 amp at 120 VAC
Optional: All double pole, double throw type (DPDT).

Ratings: UL and CSA listed.
10 amp at 125/250 VAC (form ZZ);
1/2 H.P. at 125 VDC; $3 / 4$ H.P. at 250 VAC
Limit Switches (DCR Models)
Ratings: Ratings: UL and CSA listed. MIL-PRF-8805 Qualified Listing 25 amp at 277 VAC; 1 H.P. at 125 VAC;

$$
2 \text { H.P. at } 250 \text { VAC }
$$

## Isolation Relays

To operate multiple actuators in parallel from a single signal requires isolating relays in the actuator or the field wiring.

## Heater

Thermostatically controlled PTC heater is standard in all AC voltage models.

## Part-Turn Electric | Multi-Turn Electric

220 \& 440 VAC, 3 Phase, 60 Hz.

| Model | Output Torque Inch Pounds (N.m) | Type | $\begin{gathered} \text { Speed of Operation } \\ 60 \mathrm{~Hz} .(50 \mathrm{~Hz} .) \end{gathered}$ | Duty Cycle Rating $230 \mathrm{Vac}, 3 \mathrm{Ph} .$,60 Hz . | Duty Cycle Rating 460 Vac, 3Ph., 60 Hz . | Current Ratings 220 VAC |  | Current Ratings 440 VAC |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | NLA* | LRA* | NLA* | LRA* |
| MAR 100-16 | 1,500 (169) | Part Turn | 16 seconds $/ 90^{\circ}$ <br> (19 seconds/90 ${ }^{\circ}$ ) | 25\% | 25\% | 0.34 | 1.20 | 0.15 | 0.75 |
| $\begin{gathered} \text { MAR } 120- \\ 1.25 \end{gathered}$ | 1,500 (169) | Part Turn | 1.25 seconds $/ 90^{\circ}$ <br> ( 2 seconds $/ 90^{\circ}$ ) | 25\% | 25\% | 1.60 | 3.50 | 0.82 | 1.80 |
| MAR 1201.25 MT | 1,500 (169) | MultiTurn | 12 RPM (10 RPM) | 25\% | 25\% | 1.60 | 3.50 | 0.82 | 1.80 |
| MAR 160-8 | 1,920 (217) | Part Turn | $\begin{gathered} 8 \text { seconds } / 90^{\circ} \\ \left(9 \text { seconds } / 90^{\circ}\right) \end{gathered}$ | 25\% | 25\% | 0.34 | 1.20 | 0.15 | 0.75 |
| MAR 160-16 | 2,000 (226) | Part Turn | 16 seconds $/ 90^{\circ}$ $\left(19\right.$ seconds $\left./ 90^{\circ}\right)$ | 25\% | 25\% | 0.34 | 1.20 | 0.15 | 0.75 |
| MAR 250-3 | 3,500 (316) | Part Turn | $\begin{gathered} 3 \text { seconds } / 90^{\circ} \\ \left(4 \text { seconds } / 90^{\circ}\right) \end{gathered}$ | 25\% | 25\% | 1.60 | 3.50 | 0.82 | 1.80 |
| MAR 2503MT | 3,500 (316) | MultiTurn | 5 RPM (4 RPM) | 25\% | 25\% | 1.60 | 3.50 | 0.82 | 1.80 |
| MAR 250-16 | 4,000 (452) | Part Turn | 16 seconds $/ 90^{\circ}$ $\left(19\right.$ seconds $\left./ 90^{\circ}\right)$ | 25\% | 25\% | 0.34 | 1.20 | 0.15 | 0.75 |
| MAR 250-30 | 5,000 (565) | Part Turn | 30 seconds $/ 90^{\circ}$ $\left(35\right.$ seconds $/ 90^{\circ}$ ) | 25\% | 25\% | 0.34 | 1.20 | 0.15 | 0.75 |
| MAR 250-60 | 5,000 (565) | Part Turn | 60 seconds $/ 90^{\circ}$ <br> (70 seconds/90 ) | 25\% | 25\% | 0.34 | 1.20 | 0.15 | 0.75 |
| MAR 800-12 | 7,500 (847) | Part Turn | 12 seconds $/ 90^{\circ}$ $\left(14\right.$ seconds $/ 90^{\circ}$ ) | 25\% | 25\% | 1.60 | 3.50 | 0.82 | 1.80 |
| MAR 800-30 | 10,000 (1,130) | Part Turn | 30 seconds $/ 90^{\circ}$ <br> ( 35 seconds $/ 90^{\circ}$ ) | 25\% | 25\% | 0.34 | 1.20 | 0.15 | 0.75 |
| MAR 800-60 | 10,000 (1,130) | Part Turn | 60 seconds $/ 90^{\circ}$ <br> (70 seconds/90 ) | 25\% | 25\% | 0.34 | 1.20 | 0.15 | 0.75 |
| MAR 1600-70 | 21,000 (2,373) | Part Turn | 70 seconds $/ 90^{\circ}$ <br> ( 80 seconds $/ 90^{\circ}$ ) | 25\% | 25\% | 1.60 | 3.50 | 0.82 | 1.80 |
| MAR 4000160 | 48,000 $(5,424)$ | Part Turn | 170 seconds $/ 90^{\circ}$ <br> (200 seconds/90 $)$ | 25\% | 25\% | 1.60 | 3.50 | 0.82 | 1.80 |
| * (N.L.A.) - No Lo | A Ampere (L | L.R.A.) - Locked Rotor Ampere (1) |  | 1) - Open/Close Service | (2) - Open/Close or Positioning Service |  |  |  |  |

## Isolation Relays

To operate multiple actuators in parallel from a single signal requires isolating relays in the actuator or the field wiring.

## Duty Cycle

The percentage of time the electric motor is energized vs. the time it is at rest, in reversing duty, and with the actuator running at it's rated load maximum published torque.

## Standard Modulating Duty Rating

12 motor starts (corrections) per minute at the rated duty cycle for that model with the speed of operation a minimum of 15 seconds for $90^{\circ}$ or slower with positioning accuracy of (+/-) $1 \%$ of total span.

Note - Multi-turn models are available with the following number of turns: $1.4,5,8,13,18,26$ or 50 . Must be specified when the order is placed.

## Spring Return Electric

Optional Manual Override Available


NEMA 4 Enclosure
A.C. Models Only
(Canadian Standards Association)
CSA NRTL/C Type 4


NEMA 7 Enclosure

| NEMA 7 Enclosure |  |
| :--- | :--- |
| A.C. Models Only |  |
| (Canadian Standards Association) |  |
| CSA NRTL/C | Class I, Division 1, <br> Groups C \& D |
| CSA NRTL/C | Class II, Division 1, <br> Groups E, F, \& G |
| CSA NRTL/C | Approved to UL Standard <br> No. 429, Electrically Operated <br> Values |
| CSA NRTL/C | Approved to UL Standard No. <br> 1203, Electrical Equipment <br> for use in Explosion - proof <br> And Dust - Ignition - proof <br> Hazardous (Classified) <br> Locations |


| Models |
| :---: |
| SURE 24, SURE 25 |
| Typical Applications |
| For For open / close and positioning control of: <br> - Quarter-turn ball, butterfly, plug valves or rotary dampers when emergency shutdown or shutoff capability is required in the event of a loss of power. |
| Temperature Range |
| $\begin{array}{r} \text { Standard: }-40^{\circ} \mathrm{F} \text { to }+150^{\circ} \mathrm{F} \\ -40^{\circ} \mathrm{C} \text { to }+65^{\circ} \mathrm{C} \end{array}$ |
| $\begin{aligned} \text { Optional: } & -60^{\circ} \mathrm{F} \text { to }+150^{\circ} \mathrm{F} \\ & -50^{\circ} \mathrm{C} \text { to }+65^{\circ} \mathrm{C} \end{aligned}$ |
| Optional: Compliance to NFPA 130 and NFPA 502, capable of operation after exposure to ambient temperature of $482^{\circ} \mathrm{F}$ $\left(250^{\circ} \mathrm{C}\right)$ for a minimum of 1 hour |
| Voltage |
| 115 VAC, 1 Phase, $50 / 60 \mathrm{~Hz}$ 230 VAC, 1 Phase, 50/60 Hz |
| Torque Range |
| 300 pound inches spring end ( 34 newton meters) |
| Speed Range |
| 5 \& 10 seconds for $90^{\circ}$ revolution, motor operation 2 to 5 seconds spring operation |
| Spring |
| Flat, spring steel torsion spring, XYLAN ${ }^{\circ}$ coated |
| Standard Features |
| AC Voltages 2 - SPDT Switches, Thermostatically controlled PTC heater, Motor Brake |



SURE 24


SURE 25

## Spring Return Electric

Outline Dimensions (Inches) - SURE 24/25

| Weight |
| :--- |
| $23 \mathrm{lbs} / 10.4 \mathrm{~kg}$ |



## Mounting Geometry - Bottom View




## Notes

1. Direction of rotation is based on viewing actuator from top.
2. Drawing shows actuator output shaft in power fail clockwise position.
3. Standard unit fails clockwise (closed).
4. Optional unit fails counter-clockwise (open).

NEMA 4 cover shown.
Dimensions given are accurate for NEMA 7.

## Spring-Return Electric Actuator



| NEMA 4/6/7 Enclosure |  |
| :--- | :--- |
| Approvals |  |
| $\begin{array}{l}\text { A.C. Models Only } \\ \text { (Canadian Standards Association) }\end{array}$ |  |
| CSA | Type 4 and 6 |
| NRTL/C |  |\(\left.\quad $$
\begin{array}{ll}\hline \text { CSA }\end{array}
$$ \quad \begin{array}{l}Class I, Division 1 \& 2, <br>

Groups C \& D\end{array}\right]\)


| Models |
| :---: |
| SURE 65 |
| Typical Applications |
| For open / close and positioning control of: <br> - Quarter-turn ball, butterfly, plug valves or rotary dampers when emergency shutdown or shutoff capability is required in the event of a loss of power |
| Temperature Range |
| $\begin{array}{\|r\|} \text { Standard: }-40^{\circ} \mathrm{F} \text { to }+150^{\circ} \mathrm{F} \\ -40^{\circ} \mathrm{C} \text { to }+65^{\circ} \mathrm{C} \end{array}$ |
| $\begin{aligned} \text { Optional: } & -60^{\circ} \mathrm{F} \text { to }+150^{\circ} \mathrm{F} \\ & -50^{\circ} \mathrm{C} \text { to }+65^{\circ} \mathrm{C} \end{aligned}$ |
| Optional: Compliance to NFPA 130 and NFPA 502, capable of operation after exposure to ambient temperature of $482^{\circ} \mathrm{F}$ $\left(250^{\circ} \mathrm{C}\right.$ ) for a minimum of 1 hour |
| Voltage |
| 115 VAC, 1 Phase, $50 / 60 \mathrm{~Hz}$ 230 VAC, 1 Phase, $50 / 60 \mathrm{~Hz}$ |
| Torque Range |
| 780 pound inches spring end (84 newton meters) |
| Speed Range |
| 10 and 30 seconds for $90^{\circ}$ revolution, motor operation 3 seconds spring operation |
| Spring |
| Spring steel, EVERLUBE ${ }^{\circ}$ <br> 620C coated |
| Standard Features |
| AC Voltages 4 - SPDT Switches, Thermostatically controlled PTC heater, Motor Brake |

## Spring-Return Electric Actuator

Outline Dimensions (Inches) - SURE 65


## Spring Return Electric

Optional Manual Override Available


Approvals
A.C. Models Only
(Canadian Standards Association)

| CSA NRTL/C | Type 4/4X/6 |
| :---: | :--- |
| CSA NRTL/C | Class I, Division 1, <br> Groups C \& D |
| CSA NRTL/C | Class II, Division 1, <br> Groups E, F \& G |
| CSA NRTL/C | Approved to UL Standard <br> No. 429, Electrically <br> Operated Valves |

CSA NRTL/C Approved to UL Standard No. 1203, Electrical Equipment for use in Explosion - proof And Dust - Ignition - proof Hazardous (Classified) Locations
ATEX Ex db IIB T5 Gb; Explosive gas atmosphere / Flameproof enclosure / Gas group IIB / Temperature code T5 / Zone 1

Ex tb IIIC $785^{\circ} \mathrm{CDb}$; Explosive dust atmosphere / dust tight enclosure / Dust group IIIC / Temp code $\mathrm{T} 85^{\circ} \mathrm{C}$ / Zone 21
Ambient temperature range: $-20^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}$ ( $-4^{\circ} \mathrm{F}$ to $+150^{\circ} \mathrm{F}$ )
CE Certified

| Models |
| :---: |
| SURE 100 |
| Typical Applications |
| For open / close and positioning control of: <br> - Quarter-turn ball, butterfly, plug valves or rotary dampers when emergency shutdown or shutoff capability is required in the event of a loss of power |
| Temperature Range |
| $\begin{aligned} & \text { Standard: }-40^{\circ} \mathrm{F} \text { to }+150^{\circ} \mathrm{F} \\ &-40^{\circ} \mathrm{C} \text { to }+65^{\circ} \mathrm{C} \end{aligned}$ |
| $\begin{aligned} \text { Optional: } & -60^{\circ} \mathrm{F} \text { to }+150^{\circ} \mathrm{F} \\ & -50^{\circ} \mathrm{C} \text { to }+65^{\circ} \mathrm{C}\end{aligned}$ |
| Optional: Compliance to NFPA 130 and NFPA 502, capable of operation after exposure to ambient temperature of $482^{\circ} \mathrm{F}$ ( $250^{\circ} \mathrm{C}$ ) for a minimum of 1 hour |
| Voltage |
| 115 VAC, 1 Phase, 50/60 Hz. 230 VAC, 1 Phase, 50/60 Hz. |
| Torque Range |
| 1200 pound inches spring end (136 newton meters) |
| Speed Range |
| 10 \& 30 seconds for $90^{\circ}$ revolution, motor operation 5 to 7 seconds spring operation |
| Spring |
| Helical torsion spring, spring steel, XYLAN ${ }^{\circ}$ coated |
| Standard Features |
| AC Voltages 4 - SPDT Switches, Thermostatically controlled PTC heater, Motor Brake |



## Spring Return Electric

Outline Dimensions (Inches) - SURE 100

| Weight |
| :--- |
| NEMA 4/4X/6/7 Enclosure: $77 \mathrm{lbs} / 35 \mathrm{~kg}$ |



Conduit Entries

## Conduit Entries

## Notes

1. Direction of rotation is based on viewing actuator from top.
2. Actuator shown in a power fail position. Two keys are recommended for driving device.
3. It is recommended that the actuator be driven electrically in both directions for normal operartion and prolonged life.

## Spring Return Electric

Optional Manual Override Available

|  |  |
| :---: | :---: |
|  | A 4/6/7 Enclosure |
|  | Approvals |
| CSA NRTL/C | Class I, Division 1, Groups C \&D |
| CSA NRTL/C | Class II, Division 1, Groups E, F \& G |
| CSA NRTL/C | Approved to UL Standard No. 1203, CSA C22.2 No. 25-1966, CSA C22.2 No. 30-M1986 <br> Electrical Equipment for use in Explosion-proof and Dust Ignition-proof Hazardous (Classified) Locations |
| CSA NRTL/C | Approved to UL Standard No. 508, CSA C22.2 No. 14-13, Industrial Control Equipment |
| ATEX | Ex db IIB T5 Gb; Explosive gas atmosphere / Flameproof enclosure / Gas group IIB / Temperature code T5 / Zone 1 <br> Ex tb IIIC $85^{\circ} \mathrm{C}$ Db; Explosive dust atmosphere / dust tight enclosure / Dust group IIIC / Temp code $\mathrm{T} 85^{\circ} \mathrm{C}$ / Zone 21 <br> Ambient temperature range: $-20^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}$ ( $-4^{\circ} \mathrm{F}$ to $+150^{\circ} \mathrm{F}$ ) <br> CE Certified |


| Models |
| :---: |
| SURE 150 |
| Typical Applications |
| For open / close and positioning: <br> - Quarter-turn or rotary movement when emergency shutdown or shutoff capability is required in the event of a loss of power |
| Temperature Range |
| $\begin{aligned} & \text { Standard: }-40^{\circ} \mathrm{F} \text { to }+150^{\circ} \mathrm{F} \\ &-40^{\circ} \mathrm{C} \text { to }+65^{\circ} \mathrm{C} \end{aligned}$ |
| Optional: Compliance to NFPA 130 and NFPA 502 , capable of operation after exposure to ambient temperature of $482^{\circ} \mathrm{F}$ $\left(250^{\circ} \mathrm{C}\right)$ for a minimum of 1 hour |
| Voltage |
| ```115 VAC, 1 Phase, 50/60 Hz. 230 VAC, 1 Phase, 50/60 Hz.``` |
| Torque Range |
| 1800 pound inches spring end (204 newton meters) |
| Speed Range |
| 15 seconds for $90^{\circ}$ revolution, motor operation 5 seconds spring operation |
| Spring |
| Helical torsion spring, spring steel, XYLAN ${ }^{\circ}$ coated |
| Standard Features |
| AC Voltages 4 - SPDT Switches, Thermostatically controlled PTC heater, Motor Brake |



## Spring Return Electric

Outline Dimensions (Inches) - SURE 150

| Weight |
| :--- |
| $120 \mathrm{lbs} / 54.5 \mathrm{~kg}$ |



Conduit Entries

## Conduit Entries

## Notes

1. Direction of rotation is based on viewing actuator from top.
2. Actuator shown in a power fail position.
3. Two keys are recommended for driving device.
4. It is recommended that the actuator be driven electrically in both directions for normal operartion and prolonged life.

driving device.

CCW Spring
Return

[^0]
## Spring Return Electric

115 \& 230 VAC, 1 Phase, $50 / 60 \mathrm{~Hz}$.

| Model | Output Torque Inch Pounds (N.m) | Electrical Speed of Operation 60 Hz . $(50 \mathrm{~Hz}$.) | Speed of Operation 60 Hz . $(50 \mathrm{~Hz}$.) | Duty Cycle Rating 115 VAC | Duty Cycle <br> Rating <br> 230 VAC | Current <br> Ratings <br> 115 VAC |  | $\begin{aligned} & \text { Current Rat- } \\ & \text { ings } \\ & 230 \text { VAC } \end{aligned}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | NLA* | LRA* | NLA* | LRA* |
| Sure 25-5 | 300 (34) | $\begin{gathered} 5 \text { seconds } / 90^{\circ} \\ \left(6 \text { seconds } / 90^{\circ}\right) \end{gathered}$ | 2 seconds $/ 90^{\circ}$ | $50 \%$ <br> (1) | 50\% <br> (1) | 1.40 | 2.15 | CF** | CF** |
| Sure 25-10 | 300 (34) | 10 seconds/90 ${ }^{\circ}$ <br> (12 seconds/90 ) | 2 seconds $/ 90^{\circ}$ | 50\% <br> (2) | 50\% <br> (2) | 1.00 | 1.55 | CF** | CF** |
| Sure 24-10 | 300 (34) | 10 seconds/90 ${ }^{\circ}$ <br> (12 seconds/90 ) | 2 seconds/90 ${ }^{\circ}$ | $25 \%$ <br> (1) | $25 \%$ <br> (1) | 0.70 | 1.05 | 0.45 | . 065 |
| Sure 65-10 | 780 (88) | 10 seconds | 3 seconds | $45 \%$ <br> (1) | $45 \%$ <br> (1) | 1.10 | 1.90 | 0.80 | 0.98 |
| Sure 65-30 | 780 (88) | 30 seconds | 7 seconds | $75 \%$ <br> (2) | $75 \%$ <br> (2) | 0.52 | 0.89 | 0.52 | 0.89 |
| Sure 100-10 | 1,200 (136) | 10 seconds $/ 90^{\circ}$ $\left(12\right.$ seconds $\left./ 90^{\circ}\right)$ | $\begin{aligned} & 5 \text { seconds } / 90^{\circ} \\ & (\max )+ \end{aligned}$ | 25\% <br> (1) | $25 \%$ <br> (1) | 1.90 | 2.90 | 0.90 | 1.35 |
| Sure 100-30 | 1,200 (136) | 30 seconds $/ 90^{\circ}$ <br> ( 35 seconds $/ 90^{\circ}$ ) | $\begin{aligned} & 7 \text { seconds/90 } \\ & (\max )+ \end{aligned}$ | 50\% <br> (2) | $50 \%$ <br> (2) | 0.65 | 0.95 | 0.35 | 0.45 |
| Sure 150-15 | 1,800 (136) | 15 seconds/90 ${ }^{\circ}$ (18 seconds/90 ) | $\begin{gathered} 5 \text { seconds } / 90^{\circ} \\ (\max )+ \end{gathered}$ | $\begin{gathered} 25 \% \\ (1),(2) \end{gathered}$ | $\begin{gathered} 25 \% \\ (1),(2) \end{gathered}$ | 1.90 | 2.90 | 0.90 | 1.35 |

$\begin{array}{llll}\text { * (N.L.A.) - No Load Ampere } & \text { (L.R.A.) - Locked Rotor Ampere } & \text { (1) - Open/Close Service } & \text { (2) - Open/Close or Positioning Service } \\ { }^{* *} \text { (CF) - Consult Factory } & + \text { - Approximate, Based on Load } & & \end{array}$

## Limit Switches (Sure 24 \& 25)

Standard: Two-single pole, double throw type (SPDT) with an option for 2 or 4 additional.
Ratings: Ratings: UL and CSA listed. $15 \mathrm{amp} \& 1 / 2$ H.P. at 125 or 250 VAC $1 / 2 \mathrm{amp}$ at $125 \mathrm{VDC} ; 1 / 4 \mathrm{amp}$ at 250 VDC
Lamp Load: 5 amp at 120 VAC

## Isolation Relays

To operate multiple actuators in parallel from a single signal requires isolating relays in the actuator or the field wiring.

## Limit Switches (Sure 65,100, and 150)

Standard: Four-single pole, double throw type (SPDT) with an option for 2 additional.
Ratings: Ratings: UL and CSA listed. $15 \mathrm{amp} \& 1 / 2$ H.P. at 125 or 250 VAC
$1 / 2 \mathrm{amp}$ at $125 \mathrm{VDC} ; 1 / 4 \mathrm{amp}$ at 250 VDC Lamp Load: 5 amp at 120 VAC
Optional: All double pole, double throw type (DPDT).
Ratings: Ratings: UL and CSA listed. 10 amp at 125 or 250 VAC (form ZZ) 1/2 H.P. at 125 VDC; 3/4 H.P. at 250 VDC

## Heater

Thermostatically controlled PTC heater is standard in all AC voltage models.

## Duty Cycle

The percentage of time the electric motor is energized vs. the time it is at rest, in reversing duty, and with the actuator running at it's rated load - maximum published torque.

## Standard Positioning Duty Rating

12 motor starts (corrections) per minute at the rated duty cycle for that model with the speed of operation a minimum of 15 seconds for $90^{\circ}$ or slower with positioning accuracy of (+/-) $1 \%$ of total span.

## D.C. Analog - ACT-100 Module



## Application

The ACT-100 module provides accurate positioning control of electric motor actuators using an analog input signal. Setup and calibration is greatly simplified using microprocessor based technology. With no dip switches to set or trim pots to adjust, setup is quick and easy using the ACT menu viewable on an LED display. No external meters are required, even for potentiometer setup. Once initial menu settings are chosen, the ACT-100 performs a self-calibration routine, applying the menu selections to actual actuator performance. Calibration values are then stored in permanent non-volatile memory.

## Features

Mounts internally in all RCS actuator models: MAR-10, MAR-50, MAR-90, MAR-100, MAR-160, MAR-250, MAR-800 \& all SurePowr models.

- Onboard LED display facilitates setup and calibration using the ACT-100 Menu Setup process
- Menu selection selection of input/output ranges including $4-20$ mAdc, $1-5 \mathrm{Vdc}, 2-10 \mathrm{Vdc}$, and $0-10 \mathrm{Vdc}$, or virtually any custom range required
- Automatic calibration feature: no resistors to add, no jumpers, trim pots, or dip switches to configure. Calibration is as simple as the push of a button.
- Menu selectable fail options
- Intelligent positioning reduces motor cycling, increases motor life and extends the actuator duty
- Optional Modbus RTU remote control over a RS-485 network. Complete access to all controller functions from your factory automation system
- Quick disconnect terminal strips facilitate fast and easy actuator maintenance and troubleshooting
- Always wires the same; no need to determine rotation direction during installation; rotation is selected using the selection menu during calibration mode.


## Specifications

## Power Requirements

Model ACT 100-115/230A
Single phase, 115 or 230 VAC $50 / 60 \mathrm{~Hz}$. (Jumper selectable)

## Input Command Signal

Menu selectable factory defaults:

- 4-20 mADC
- 1-5 VDC
- 2-10 VDC
- 0-10 VDC

Infinite adjustment using ACT menu system

## Signal Impedance

Input: $250 \Omega$ current, $200 \mathrm{~K} \Omega$ voltage
Output: Maximum load 500 ohms current, 500 ohms voltage
Power Output
Solid state, isolated from the input command signal and rated at:

- 5 amps continuous at 115 VAC
- 5 amps continuous at 230 VAC

All ratings assume the ACT-100 module is mounted on the actuator base plate

## Sensitivity

Fully adjustable from $0.5 \%$ of total span; factory default set to $1 \%$ of total span

## Dead Band

Automatically set during the calibration process. factory default is $1 \%$ of total span, and additional settings are available using the ACT menu system.

## Zero Span Adjustment

Automatically set during calibration and fully open positions and input calibration is automatically adjusted.

## Split Range

Settable within the span range using at least 1.5 VDC or 3 mA of input.

## Remote Control

Optional Modus RTU control of all controller functions over a RS-485 multi-drop network

## Ambient Temperature

$-40^{\circ} \mathrm{F}$ (with heater) to $+150^{\circ} \mathrm{F}\left(-40^{\circ} \mathrm{C}\right.$ to $\left.+65^{\circ} \mathrm{C}\right)$

## Action on Loss of Command Signal

Factory default:

- Fail in last position (no movement)

Additional settings available at setup:

- Fail open (maximum signal value)
- Fail closed (minimum signal value)
- Fail to a preset position


## Size

W-3.70" (94mm)
H-4.10" 104.14 mm )
D - $1.63^{\prime \prime}$ ( 41.4 mm )

## Relay Outputs:

Three dry contact outputs:

- Fault indicating loss of power, Fuse failed, command signal loss or failure to move to position in preset time
- End of travel CCW
- End of travel CW
—Contacts are rated for 1 A @ 30 VDC, $0.5 \mathrm{~A} @ 135$ VAC resistive.


## Profibus D.P.



| Model |
| :--- |
| DPC-100 |
| 12 or 24 Volt D.C. Actuators |


| Model |
| :--- |
| DPC-120 |
| 115 Volt A.C. Actuators |

## Features

- Two wire control reduces installation and start up time compared to multi-cable wiring
- Automatic calibration cuts down on start up time
- No deadband eliminates need for field adjustment.
- On line configuration of 36 operational parameters using generic Profibus software
- Low power consumption; does not require ventilation
- Electronic overload protection with built-in current monitoring
- LED indicators for input, outputs and communication channel
- Automatic calibration with local pushbutton or remote command
- Dynamic breaking eliminates overshooting
- Robust power switching components, designed specifically for actuator motors, virtually eliminates field failures


## Specifications

## Power Supply

DPC-100: 24/12 VDC
DPC-120: 115 VAC

## Communication Interface

Profibus Standard

## Protocol

Profibus DP (Distributed Process)

## Feedback

Potentiometer 1000 Ohms/Optical Encoder

## Position Input Accuracy

1.0\% full scale standard, Maximum 0.1\%

Temperature
$-40^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}\left(-40^{\circ} \mathrm{F}\right.$ to $\left.+158^{\circ} \mathrm{F}\right)$

## Relative Humidity

0 to 90\% non-condensing

## Dimensions

DPC-100: $4.0 \times 1.5 \times 2.5 \mathrm{in}$. DPC-120: $4.25 \times 1.75 \times 3.75 \mathrm{in}$..
The DPC-100 \& DPC-120 provide the following status and fault signals:
Valve full closed
Valve full open
Percentage of open
Valve seeking position
Motor running
Valve closing
Valve opening
Motor thermostat tripped
Incomplete travel
Valve opening or closing manually
Valve jammed/current limiting
Motor still energized after stop or end of travel
Controller self-test (detects problems)
Communication failure
Average running current load
Peak running current load
Idle current load

## Devicenet ${ }^{\text {m }}$



## Application

For on/off or positioning control of motorized valves. DeviceNet ${ }^{\prime \prime \prime}$ is a type of communication network that allows up to 63 field devices to be linked together with a singe five-conductor cable. DeviceNet ${ }^{\text {m }}$ is a product of Allen-Bradley and is an open, nonproprietary, bus network. Typically, a DeviceNet'" system is used with the Allen-Bradley PLC5 and SLC series of programmable logic controllers. A standard DeviceNet'" Scanner interface is available for both types. Devices in the field are connected via a drop line to a 5 conductor trunk-line that is then routed to the scanner card.

## Features

- Provides open/stop/close or positioning control with limit switch status feedback
- Provides instantaneous motor reversal protection
- Command and end-of-travel verification alarm
- Conforms to ODVA standard
- Easy-to-see LED indicators for all control outputs, status inputs and diagnostic alarm
- ESD functions for 'go open', 'stay put', or 'go closed'


## Specifications

Hardware Specifications
Supply Power: 10-15 VDC
Operating Temperature: $-40^{\circ} \mathrm{C}$ TO $+90^{\circ} \mathrm{C}$
Storage Temperature: $-40^{\circ} \mathrm{C}-80^{\circ} \mathrm{C}$
Humidity: $90 \%$ Non Condensing
Solid State Outputs: (2) Isolated 600VAC 15A
Digital Inputs: (8) Dry Contacts
Analog Inputs: (2) Channels (see below)
RAM: 1K
Flash: 32K
EEPROM: 32 K

## Serious Interfaces

One CAN 2.0 port.
Network Communication Protocols
Module Supports DeviceNet"' Group 2 Slave.

## Analog Inputs Specification

Resolution: 10 Bit
Accuracy: 1\% of FS.
Linearity: $1 \%$ of FS.
Temperature Drift: $2 \%$ of FS.
Range: 0 to 5 V or $0-20 \mathrm{~mA}$ input for Al1 1-5K Potentiometer for the Position Feedback.

## Technical Summary of DeviceNet ${ }^{\text {m' }}$

Network Size: Up to 64 nodes (including scanner)
Network Length: Up to $1,640 \mathrm{ft}$. at 125 Kbps .
Data Packets: 0-8 bytes
Bus Topology: Trunkline/Dropline
Cable: 5-Conductor cable (2 for power, 2 for communication, and 1 for ground).

Thick Trunk Lines: Belden 3082A or 3083A
Thin Drop Lines: Belden 3084A or 3085A
Drop Lines: Max. drop length is 20 ft . with cumulative drop length of 512 ft .
Repeaters: Not currently, but expected in future revisions of specifications.

## Input/Output Listing

| Digital Input Status: |  |
| :--- | :--- |
| Bit 0 | Communication Loss |
| Bit 1 | Reserved |
| Bit 2 | Loss of Position Signal |
| Bit 3 | Motor Stall |
| Bit 4 | Limit Calibration Incorrect |
| Bit 5 | Thermostat Trip |
| Bit 6 | Manual Operation |
| Bit 7-15 | Reserved |

## Environmental

 Temperature Range:Storage: $-40^{\circ} \mathrm{C}$ to $+80^{\circ} \mathrm{C}$ Operating: $-40^{\circ} \mathrm{C}$ to $+90^{\circ} \mathrm{C}$
Humidity Range:
$0 \%$ to $95 \%$ at $25^{\circ} \mathrm{C}$
non-condensing

## Modbus


(Above shown with optional current sensing option).

## Features

- High resolution position input for up to $0.1 \%$ accuracy
- 4-120/240VAC inputs for open and closed limit switches and 2 general purpose inputs
- Simple 4-wire Modbus-485 communication network includes supervisory power
- Robust communication, up to 500 m cable length
- Plugable terminal strips for easy field installation
- Direct mounting within the actuator
- Low power consumption; does not require ventilation
- Electronic overload protection with built-in current monitoring optional
- High power outputs can directly drive small motors
- LED indicators on inputs, outputs and communication channel
- Automatic calibration using local push button or remote command
- Multi-vendor PLC support through the standard Modbus communication module


## Typical Applications

- Blending of bulk materials
- Petroleum products and other liquids flow control
- Level control for maintaining process supply


## Application

The Modbus is an application specific controller, designed for positioning electric actuators using rotary feedback. Typical devices include rotary and linear actuators. Feedback may be via a potentiometer or a quadrature optical encoder. Controller outputs can drive small electric motors or motor starters directly.
A Modbus-485 communication network allows up to 100 devices on a single channel. The Modbus is powered by 24VDC and provides four supervisory inputs, configurable as limit switches or force open/close signals.
Automatic calibration is provided which requires no loop tuning. All operating parameters can be set as registers in the Modbus communications map.

## Specifications

## Actuator

Voltage 120/240VAC $1 \varnothing$
Current 4A (2 minute 25\% duty-cycle)
Fuse GMA 4 replaceable

## Supervisory

Voltage 10 to 25 VDC
Current 30mA @ 24VDC

## Auxiliary Inputs

Voltage 120/240VAC
Current $\min 10 \mathrm{~mA} / \max 20 \mathrm{~mA}$

## Communication

Standard Modbus-RS485 differential
Distance 500m (1,640ft.)
Input Load 12 K ohm, standard
Termination $120 \Omega$ balanced line

## Position

Resolution 12 bit (1 part in 4096)
Accuracy 0.1\% full scale
Potentiometer $1000 \Omega$ typical ( 500 to $10 \mathrm{k} \Omega$ )
Quadrature
Optical Encoder 1000 to 4096 pulses

## Environment

Temperature $-40^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}\left(-40^{\circ} \mathrm{F}\right.$ to $\left.+158^{\circ} \mathrm{F}\right)$
Relative Humidity 0 to $95 \%$ non-condensing

## Dimensions

| Length | $96 \mathrm{~mm}(3.75 \mathrm{in})$ |
| :--- | :--- |
| Width | $70 \mathrm{~mm}(2.75 \mathrm{in})$ |
| Height | $36 \mathrm{~mm}(1.40 \mathrm{in})$ |

## Accessories

RCS electric actuators can be supplied with a selection of accessories to adapt to specific control demands and automation requirements.

- Integral potentiometer - Available in a variety of resistance ranges to interface with most common control devices; available for all models of RCS actuators.
- Auxiliary limit switches - Available in SPDT or DPDT configurations for additional control requirements and are independently adjustable.
- Interposing relays - Available with a variety of coil voltages to allow for operation when the control voltage differs from the actuator supply voltage.


## Single and dual relay configuration are available for specific applications.

- Motor brakes - Maintains actuator position and minimizes back drive created by dynamic torque in certain valve and flow applications. (Standard feature on all SurePowr models and modulating service applications)
- D.C. analog position transmitter (with integral power supply) - Provides analog position indication proportional to actuator travel.
- D.C. analog position controller - The ACT-100 analog control module is capable of being configured to a variety of common control input and output signals and features self-calibrating technology. A variety of embedded control and setting menus provide for precise settings to satisfy complex loop control demands.
- Digi-Tork bi-directional torque control - Electronic current sensing device which protects the actuator from damage created by excessive torque demands.
- Digi-Speed variable speed control - Electronic timer that allows for extension of actuator cycle time to minimize water hammer or any other piping shock created by sudden flow reversal within a piping system.
- Communication bus interface modules:
- Profibus DP
- DeviceNet ${ }^{\text {TM }}$
- Modbus
- Specialized wiring configurations - RCS actuators can be provided with internal wiring and modifications to address process requirements such as extended travel, multi-stop, interlock signals and other unique requirements.



## RCS Actuators

16240 Port Northwest Drive
Houston, TX 77041
T: 832-590-2306
Toll Free: 1-800-945-9898
F: 713-849-2879


[^0]:    CW Spring Return

